

Partitioned methods for time-dependent thermal fluid-structure interaction

Azahar Monge
Philipp Birken

Lund University

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- 1 A fast solver for thermal FSI
- 2 Limitations of the Dirichlet-Neumann method
- 3 A multirate approach

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Applications of thermal FSI

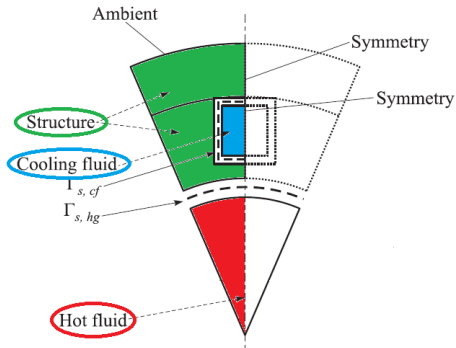
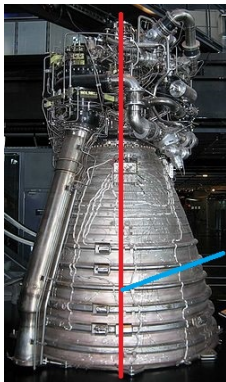
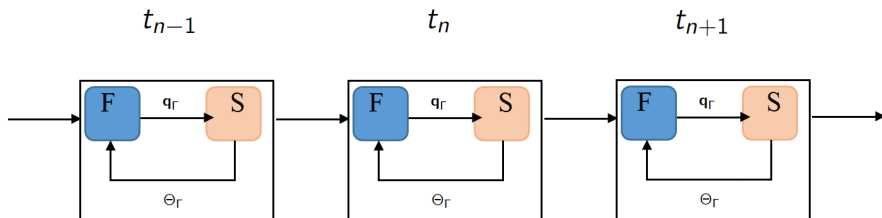


Figure: Left: Vulcain engine for Ariane 5. Right: Sketch of the cooling system; Pline, Wikimedia Commons

Thermal interaction between fluid and structure needs to be modelled

Dirichlet–Neumann coupling

- *Partitioned approach* for the solution of the coupled problem.
- *Fluid Model*: Compressible Navier–Stokes - FVM, DLR-TAU-Code
- *Structure Model*: Nonlinear heat equation - FEM, NATIVE inhouse code

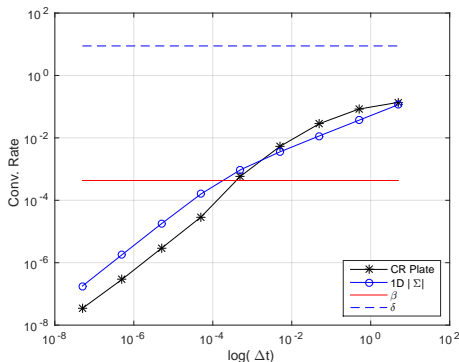


$$\Theta_r^{k+1} = \mathbf{S}(\mathbf{F}(\Theta_r^k)), \quad \text{Interface Temperature Iteration}$$

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Limitations of the Dirichlet–Neumann method

Convergence rates FSI application



Limitations

- The subsolvers are **sequential**.
- Same time integration for both fields.

Use a different method!

More at: A. Monge, P. Birken, Computational Mechanics, 2017

Limitations of the Dirichlet–Neumann method

List of wishes

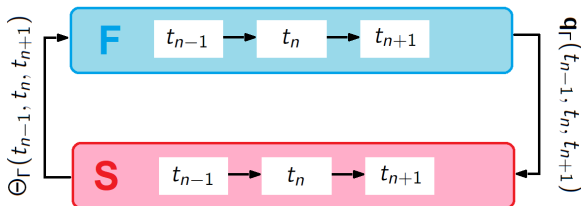
- Two **independent time integration** schemes.
- **High order** resolution (at least 2nd order).
- To be able to insert **time adaptivity** in the framework.

Option 1

Exchange **fixed point iteration** with
time recursion

Option 2

Use a different **domain**
decomposition method



Limitations of the Dirichlet–Neumann method

Option 1

Dirichlet-Neumann Waveform
Relaxation (DNWR) algorithm

- + Computationally cheap
- Sequential method

Option 2

Neumann-Neumann Waveform
Relaxation (NNWR) algorithm

- + Parallel method
- Computationally expensive

- *DNWR and NNWR introduced by Gander and Kwok 2016: Constant coefficients and one single time integration scheme.*

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Model Problem: Coupled heat equations

$$\begin{aligned}\alpha_m \frac{\partial u_m(\mathbf{x}, t)}{\partial t} - \nabla \cdot (\lambda_m \nabla u_m(\mathbf{x}, t)) &= 0, \\ t \in [t_0, t_f], \quad \mathbf{x} \in \Omega_m \subset \mathbb{R}^d, \quad m = 1, 2 \\ u_m(\mathbf{x}, t) &= 0, \quad \mathbf{x} \in \partial\Omega_m \setminus \Gamma \\ u_1(\mathbf{x}, t) &= u_2(\mathbf{x}, t), \quad \mathbf{x} \in \Gamma \\ \lambda_2 \frac{\partial u_2(\mathbf{x}, t)}{\partial \mathbf{n}_2} &= -\lambda_1 \frac{\partial u_1(\mathbf{x}, t)}{\partial \mathbf{n}_1}, \quad \mathbf{x} \in \Gamma \\ u_m(\mathbf{x}, 0) &= g_m(\mathbf{x}) \quad \mathbf{x} \in \Omega_m\end{aligned}$$

where $\alpha_m = \lambda_m / D_m$.

Dirichlet-Neumann waveform relaxation (DNWR)

$$(D) \begin{cases} \alpha_1 \frac{\partial u_1^{k+1}(\mathbf{x}, t)}{\partial t} - \nabla \cdot (\lambda_1 \nabla u_1^{k+1}(\mathbf{x}, t)) = 0, & \mathbf{x} \in \Omega_1, \\ u_1^{k+1}(\mathbf{x}, t) = 0, & \mathbf{x} \in \partial\Omega_1 \setminus \Gamma, \\ u_1^{k+1}(\mathbf{x}, t) = g^k(\mathbf{x}, t), & \mathbf{x} \in \Gamma, \\ u_1^{k+1}(\mathbf{x}, 0) = u_1^0(\mathbf{x}), & \mathbf{x} \in \Omega_1. \end{cases}$$

$$(N) \begin{cases} \alpha_2 \frac{\partial u_2^{k+1}(\mathbf{x}, t)}{\partial t} - \nabla \cdot (\lambda_2 \nabla u_2^{k+1}(\mathbf{x}, t)) = 0, & \mathbf{x} \in \Omega_2, \\ u_2^{k+1}(\mathbf{x}, t) = 0, & \mathbf{x} \in \partial\Omega_2 \setminus \Gamma, \\ \lambda_2 \frac{\partial u_2^{k+1}(\mathbf{x}, t)}{\partial \mathbf{n}_2} = -\lambda_1 \frac{\partial u_1^{k+1}(\mathbf{x}, t)}{\partial \mathbf{n}_1}, & \mathbf{x} \in \Gamma, \\ u_1^{k+1}(\mathbf{x}, 0) = u_1^0(\mathbf{x}), & \mathbf{x} \in \Omega_1. \end{cases}$$

$$(U) \quad g^{k+1}(\mathbf{x}, t) = \Theta u_2^{k+1}(\mathbf{x}, t) + (1 - \Theta)g^k(\mathbf{x}, t), \quad \mathbf{x} \in \Gamma.$$

How to choose the relaxation parameter Θ properly?

Neumann-Neumann waveform relaxation (NNWR)

$$(D_m), m = 1, 2 \begin{cases} \alpha_m \frac{\partial u_m^{k+1}(\mathbf{x}, t)}{\partial t} - \nabla \cdot (\lambda_m \nabla u_m^{k+1}(\mathbf{x}, t)) = 0, & \mathbf{x} \in \Omega_m, \\ u_m^{k+1}(\mathbf{x}, t) = 0, & \mathbf{x} \in \partial\Omega_m \setminus \Gamma, \\ u_m^{k+1}(\mathbf{x}, t) = g^k(\mathbf{x}, t), & \mathbf{x} \in \Gamma, \\ u_m^{k+1}(\mathbf{x}, 0) = u_1^0(\mathbf{x}), & \mathbf{x} \in \Omega_m. \end{cases}$$

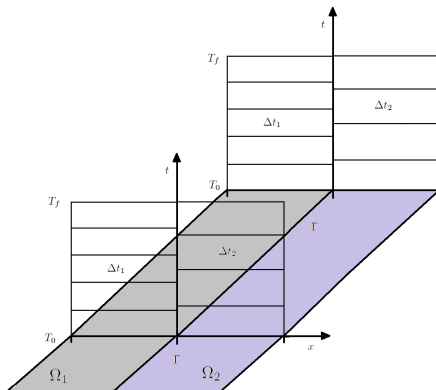
$$(N_m), m = 1, 2 \begin{cases} \alpha_m \frac{\partial \psi_m^{k+1}(\mathbf{x}, t)}{\partial t} - \nabla \cdot (\lambda_m \nabla \psi_m^{k+1}(\mathbf{x}, t)) = 0, & \mathbf{x} \in \Omega_m, \\ \psi_m^{k+1}(\mathbf{x}, t) = 0, & \mathbf{x} \in \partial\Omega_m \setminus \Gamma, \\ \lambda_m \frac{\partial \psi_m^{k+1}(\mathbf{x}, t)}{\partial \mathbf{n}_1} = \lambda_1 \frac{\partial u_1^{k+1}(\mathbf{x}, t)}{\partial \mathbf{n}_1} + \lambda_2 \frac{\partial u_2^{k+1}(\mathbf{x}, t)}{\partial \mathbf{n}_2}, & \mathbf{x} \in \Gamma, \\ \psi_m^{k+1}(\mathbf{x}, 0) = 0, & \mathbf{x} \in \Omega_m. \end{cases}$$

$$(U) \quad g^{k+1}(\mathbf{x}, t) = g^k(\mathbf{x}, t) - \Theta(\psi_1^{k+1}(\mathbf{x}, t) + \psi_2^{k+1}(\mathbf{x}, t)), \quad \mathbf{x} \in \Gamma.$$

How to choose the relaxation parameter Θ properly?

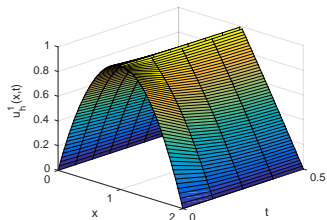
Choices

- *Space discretization*: 1D and 2D finite elements
- *Time discretization*: Implicit Euler and SDIRK2
- *Matching space grid* at the interface, unknowns on interface
- *Nonmatching time grids* at the interface, **linear interpolation**

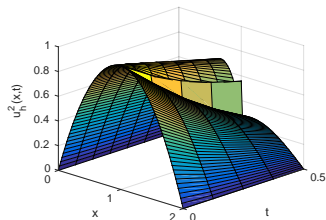


Multirate 1D solution

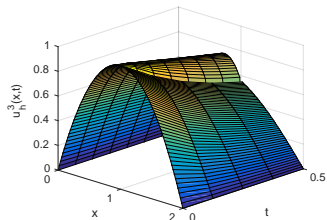
Iteration 1



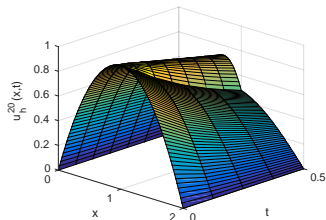
Iteration 2



Iteration 3



Iteration 20



Q: How to choose the **relaxation parameter** Θ ?

A: Find Θ s.t. **minimizes the spectral radius** of Σ w.r.t $\mathbf{u}_\Gamma(T_f)$,

$$\mathbf{u}_\Gamma^{k+1, T_f} = \Sigma \mathbf{u}_\Gamma^{k, T_f} + \sum_{i=2}^2 \left(\psi^{k+1, \tilde{\tau}_i} + \psi^{k, \tau_i} \right).$$

Procedure to find the iteration matrix

- 1 Isolate $\mathbf{u}_\Gamma^{(m), k+1, T_f}$ from the Dirichlet solver.
- 2 Isolate $\mathbf{u}_\Gamma^{(2), k+1, T_f}$ or $\psi_\Gamma^{(m), k+1, T_f}$ from the Neumann solver.
- 3 Use the update step to get Σ w.r.t $\mathbf{u}_\Gamma(T_f)$.

Iteration Matrix

After lengthy derivations one gets,

DNWR Algorithm

$$\Sigma = \mathbf{I} - \Theta \left(\mathbf{I} + \mathbf{S}^{(2)-1} \mathbf{S}^{(1)} \right),$$

NNWR Algorithm

$$\Sigma = \mathbf{I} - \Theta \left(2\mathbf{I} + \mathbf{S}^{(1)-1} \mathbf{S}^{(2)} + \mathbf{S}^{(2)-1} \mathbf{S}^{(1)} \right)$$

with

$$\mathbf{S}^{(m)} = (\mathbf{M}_{rr}^{(m)} + \Delta t \mathbf{A}_{rr}^{(m)}) - (\mathbf{M}_{rl}^{(m)} + \Delta t \mathbf{A}_{rl}^{(m)}) (\mathbf{M}_m + \Delta t \mathbf{A}_m)^{-1} (\mathbf{M}_{lr}^{(m)} + \Delta t \mathbf{A}_{lr}^{(m)})$$

for $m = 1, 2$.

Iteration Matrix

A closer look at the iteration matrix Σ :

$$\mathbf{S}^{(m)} = \mathbf{M}_{\Gamma\Gamma}^{(m)} - \Delta t \mathbf{A}_{\Gamma\Gamma}^{(m)} - \left(\mathbf{M}_{\Gamma I}^{(m)} - \Delta t \mathbf{A}_{\Gamma I}^{(m)} \right) \left(\mathbf{M}_m - \Delta t \mathbf{A}_m \right)^{-1} \left(\mathbf{M}_{I\Gamma}^{(m)} - \Delta t \mathbf{A}_{I\Gamma}^{(m)} \right)$$

- **Problem:** Matrices $\mathbf{M}_m + \Delta t \mathbf{A}_m$ are sparse but $(\mathbf{M}_m + \Delta t \mathbf{A}_m)^{-1}$ are dense.
- **Solution:** Use their eigendecompositions to compute the desired entries of the Toeplitz matrices: $(\mathbf{M}_m + \Delta t \mathbf{A}_m)^{-1} = \mathbf{V} \Lambda_m^{-1} \mathbf{V}.$

Optimal Relaxation Parameter

- *Space discretization*: 1D equidistant FE/FE.
- *Time integration*: **nonmultirate** Implicit Euler.

DNWR Algorithm

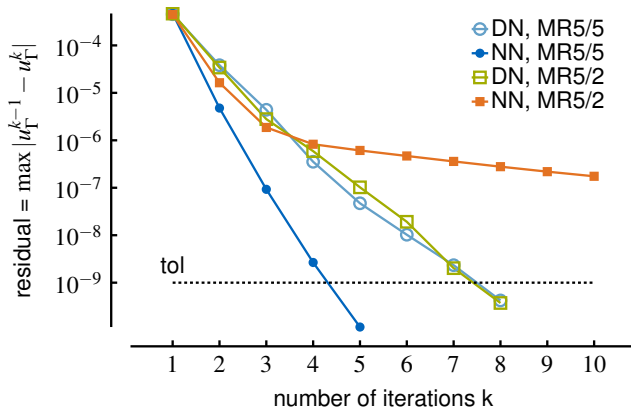
$$\Theta_{opt} = \left(1 + \frac{\mathbf{s}^{(1)}}{\mathbf{s}^{(2)}} \right)^{-1},$$

with

$$\mathbf{s}^{(m)} = (6\Delta x(\alpha_m \Delta x^2 + 3\lambda_m \Delta t) - (\alpha_m \Delta x^2 - 6\lambda_m \Delta t)^2 s_m).$$

Θ_{opt} gives the optimal parameter for any coupled materials!

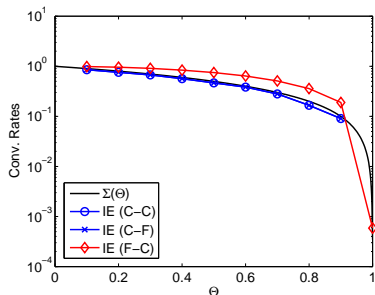
Comparison DNWR and NNWR



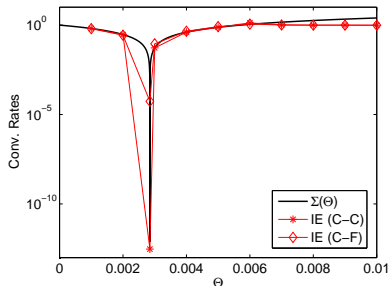
- *Nonmultirate*: NNWR performs **half** the iterations than DNWR.
- *Nonmultirate*: DNWR uses **half** the resources than NNWR.
- *Multirate*: DNWR performs better than NNWR.

Convergence Rates: Air-Water coupling

DNWR (1D case)



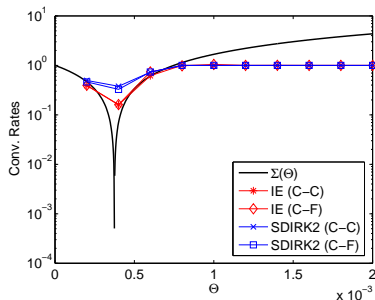
NNWR (1D case)



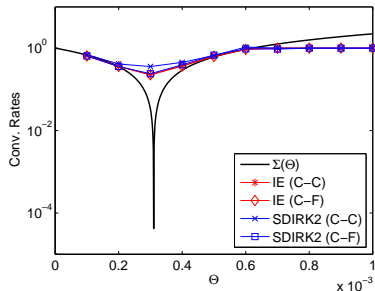
Θ_{opt} is more sensitive for NNWR than for DNWR.

Convergence Rates: NNWR in 2D

Air-Steel



Air-Water



The 1D Θ_{opt} is very good for 2D examples.

Summary and Further Work

- **Multirate parallel** method for coupled parabolic problems (NNWR).
 - **Multirate sequential** method for coupled parabolic problems (DNWR).
 - We have performed a 1D analysis to find Θ_{opt} .
 - Θ_{opt} is dependent on Δt , Δx , λ_m and α_m , $m = 1, 2$.
 - Θ_{opt} is more sensitive for NNWR than for DNWR.
 - Θ_{opt} works for 2D, multirate and **time adaptivity**.
-
- Investigate the time adaptive extension.
 - Apply to FSI test cases.
 - Load balancing.

More at: A. Monge, P. Birken, arXiv:1805.04336

Thank you!